

# Storing and analysing **massive** aerial LiDAR datasets in a DBMS

Hugo Ledoux

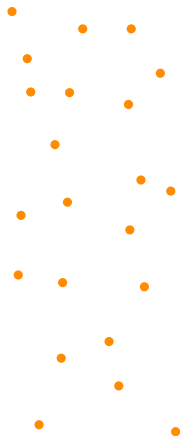


Technische Universiteit Delft

November 30 2010  
ELMF, Den Haag

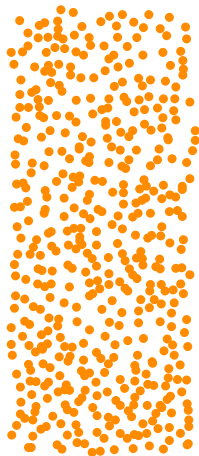
- Computers have many problems dealing with billions of points:
  - Storing is OK
  - Visualisation is still a challenge
  - **Processing** and **analysis** are very problematic
- Processing operations:
  - derivation of slope/aspect,
  - conversion to grid format,
  - calculations of area/volumes,
  - viewshed analysis,
  - creation of simplified DTM,
  - extraction of bassins,
  - etc.

Advances in technologies to collect data are far superior to our ability to process data.



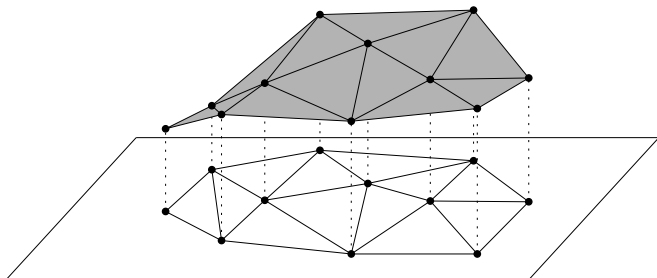
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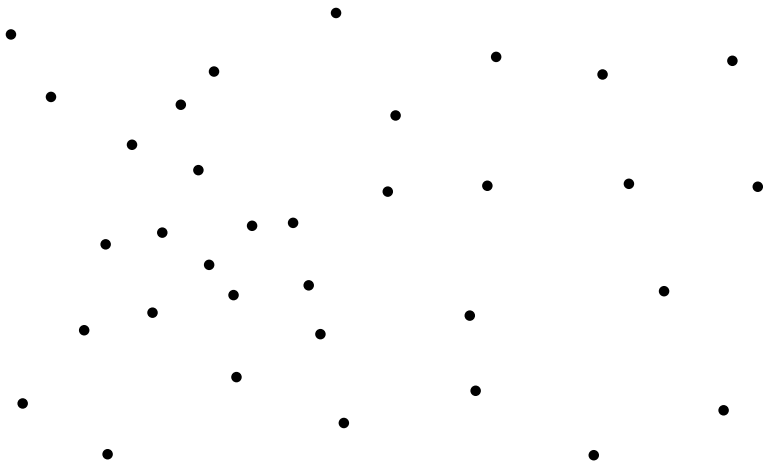


# Point clouds are often “2.5D surface”

LiDAR datasets are formed by scattered points in 3D space, which are the samples of a surface that can be projected on the horizontal plan.

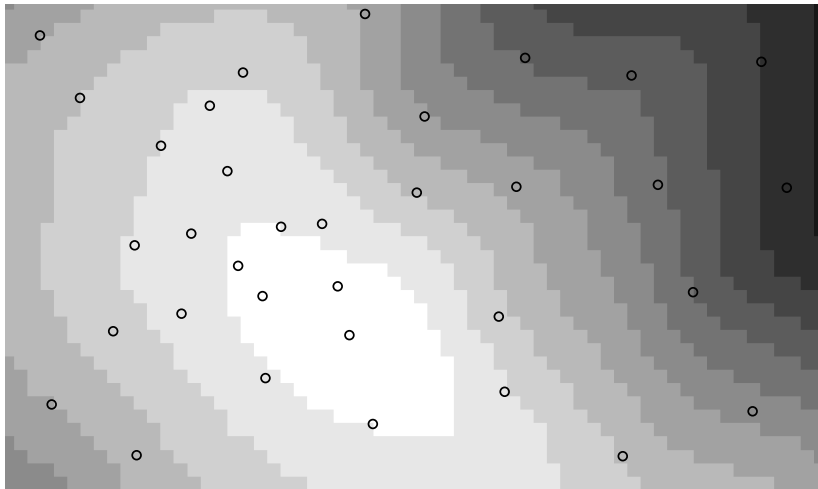


# Reconstruction of the surface



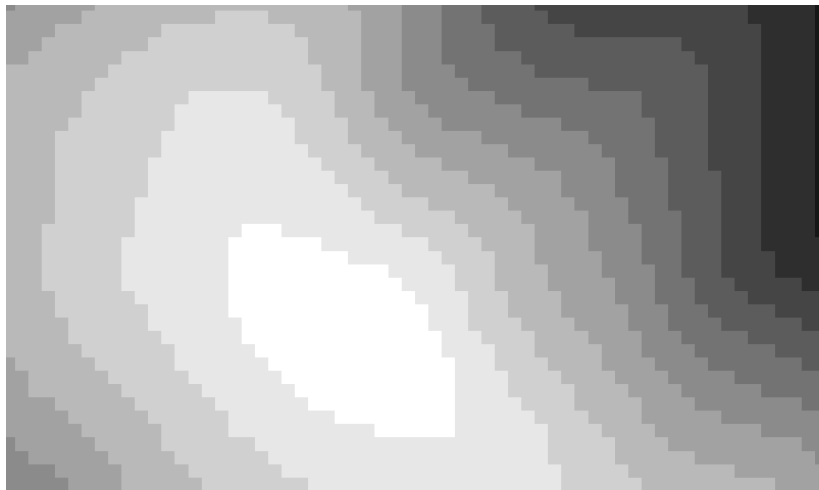
Original LiDAR points

# Reconstruction of the surface



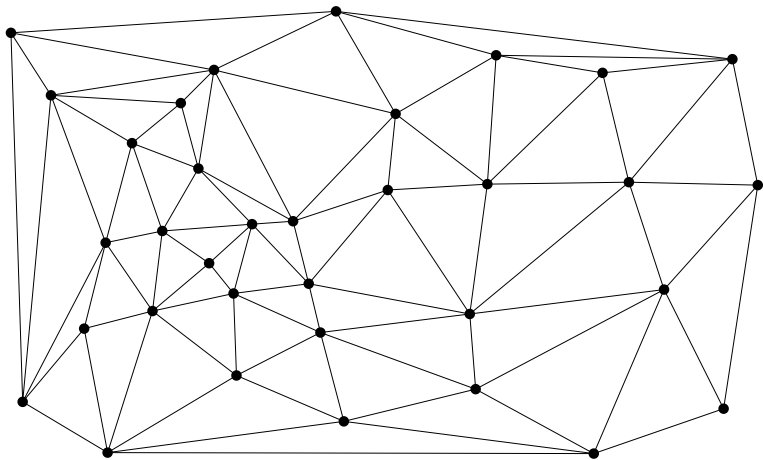
Raster representation

# Reconstruction of the surface



Raster representation

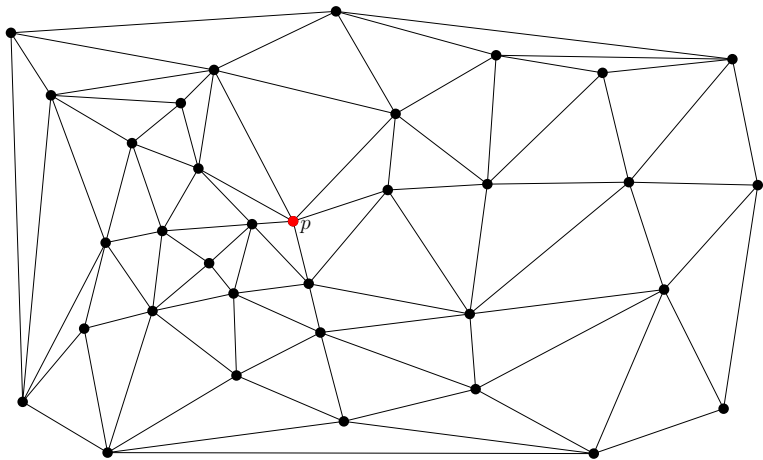
# Reconstruction of the surface



TIN (with Delaunay triangles)

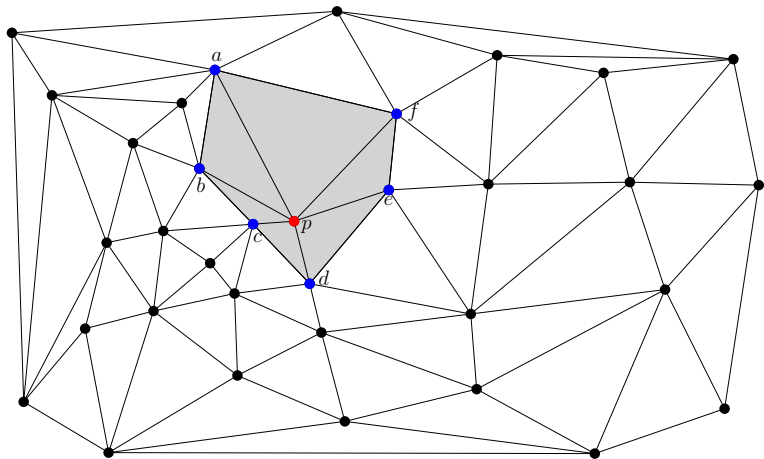


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TIN (with Delaunay triangles)

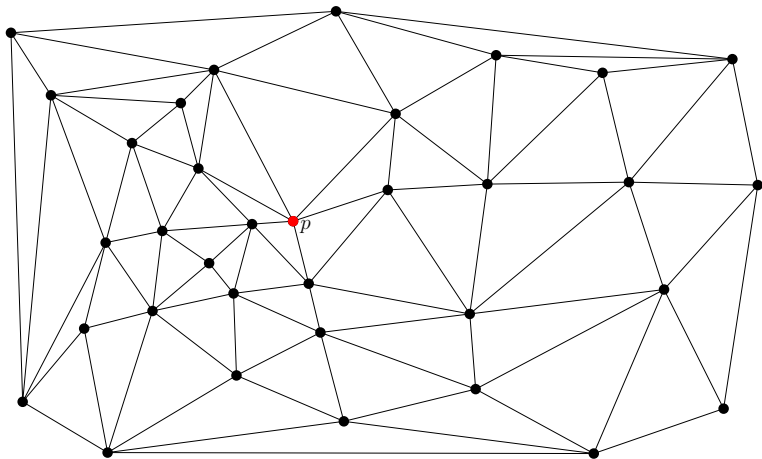
- Terrasolid: max is main memory
- ArcGIS: *Terrain* type (hierarchical structure)
- Oracle Spatial 11g: *Point Cloud & TIN* types
- External memory algorithms [AAD06, ADHZ06]
- Streaming of geometries of Isenburg *et al.* [ILSS06, ILS<sup>+</sup>06]

# Storing triangles in a DBMS

- 1 Storing independently triangles ( $\sim$  OGC)
- 2 Triangle-based data structure used by triangulation libraries [BDP<sup>+</sup>02]
- 3 Edge-based data structure (e.g. half-edge [M88])

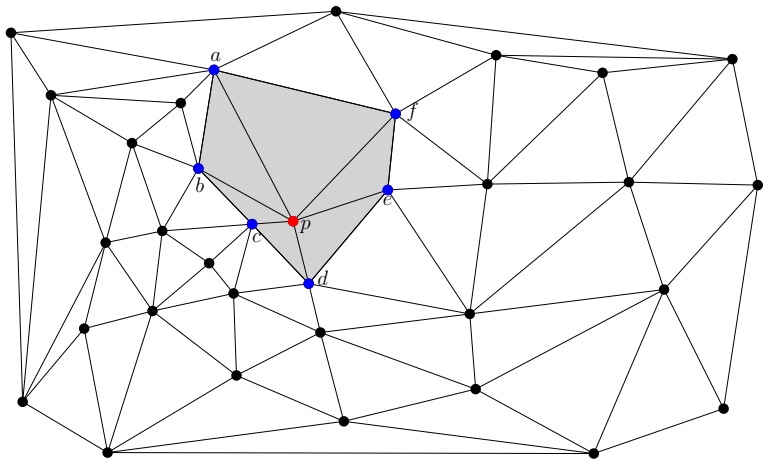
# A star-based data structure

- Goes beyond the usual “store points and edges/triangles”
- Ideas come from data structures for compression of graphs [BBCK05]



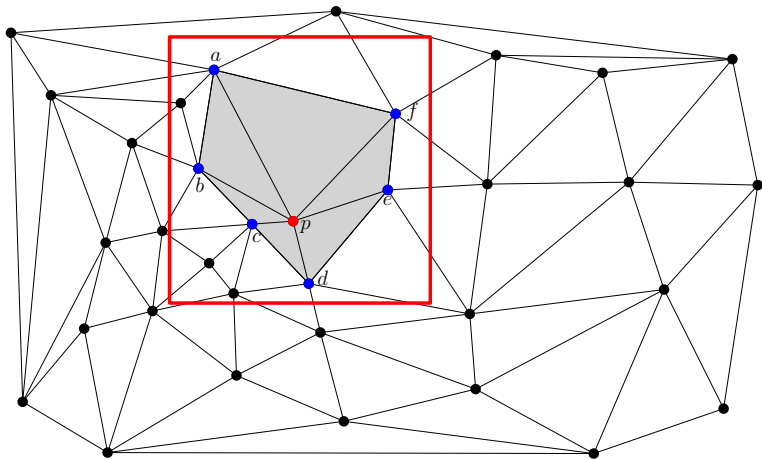
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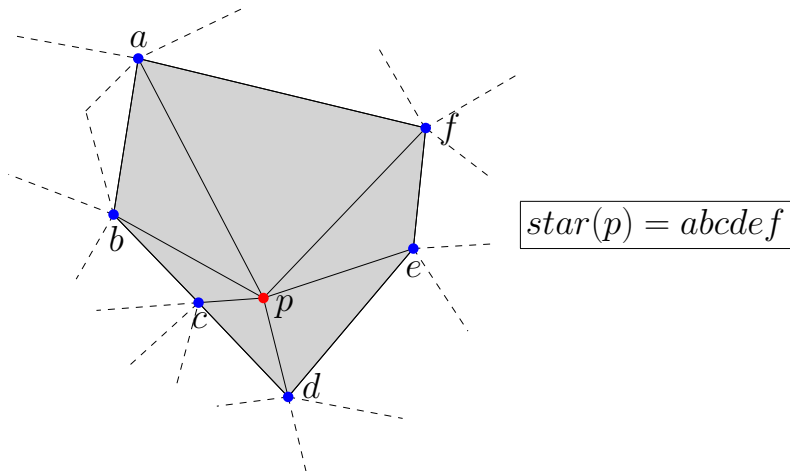
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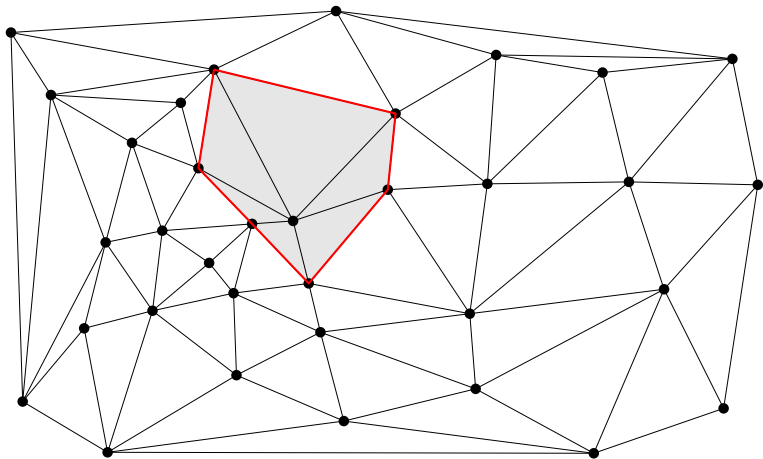
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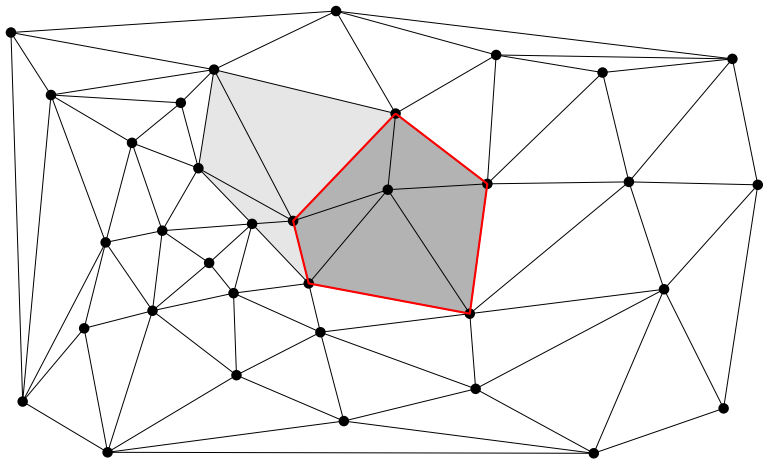




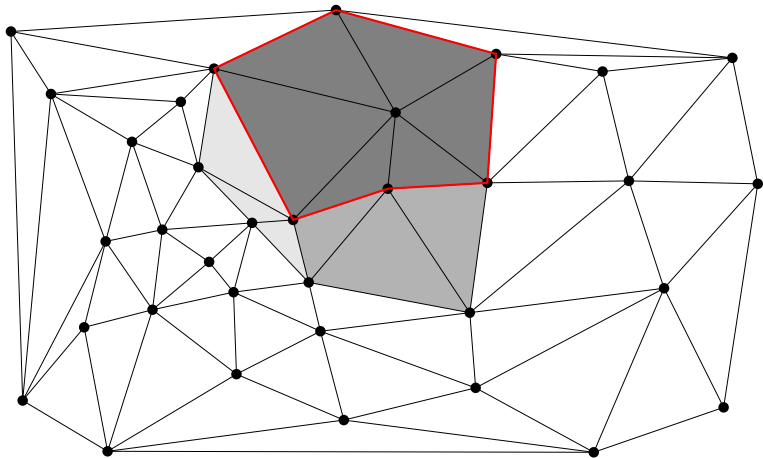
Every star( $v$ ) is stored  $\rightarrow$  implicit triangles



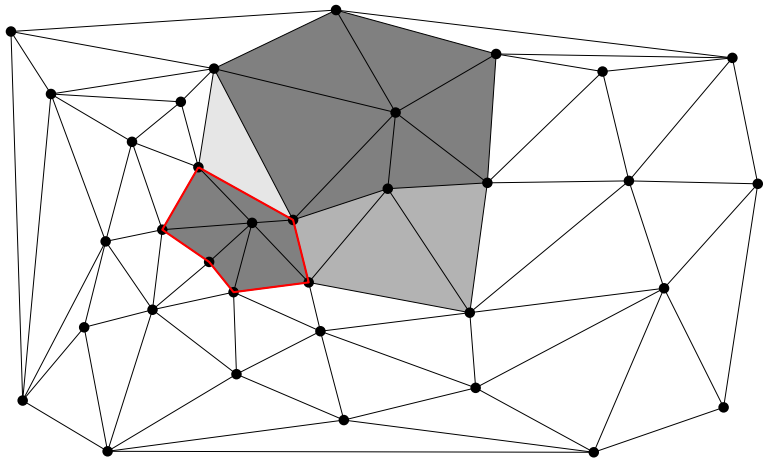
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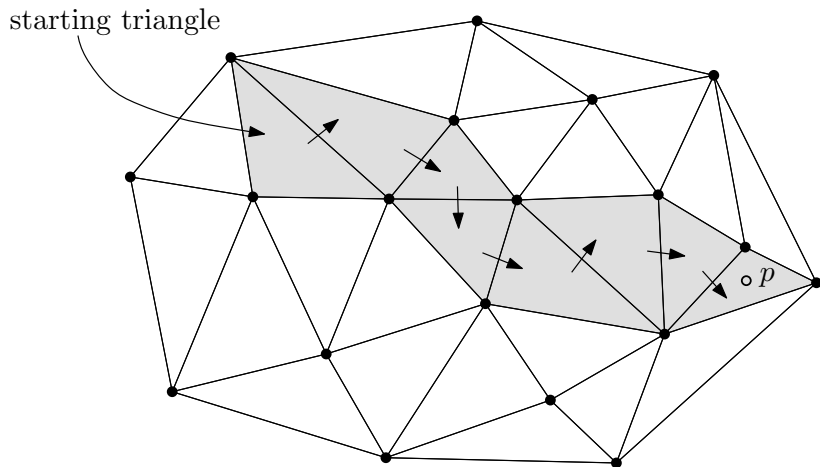


ID	x	y	z	star[]
1	3.21	5.23	2.11	[2,44,55,61,23]
2	5.19	29.01	4.55	[7,98,111,233,222]
3	22.43	15.99	8.19	[99,101,73,23]
...	...	...	...	...
5674	221.19	15.23	37.81	[309,802,793,1111]

## Advantages:

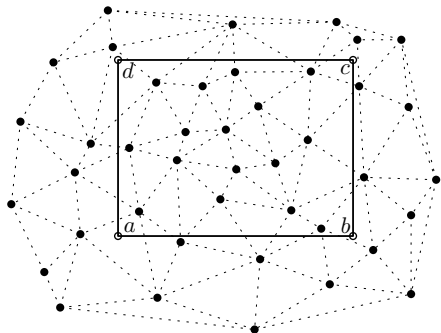
- 1 Only **one** table with  $id - x - y - z - star$
- 2 No spatial index needed: fetching of triangles based on “walking”
- 3 Star column need not be filled ( $\sim$  Simple Features)
- 4 Local updates are possible (insertion and removals)

# Point Location = “Walking” in the triangulation

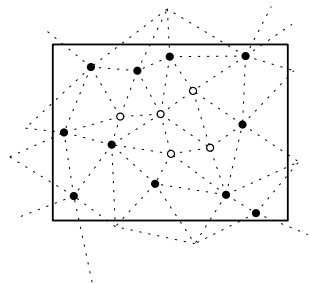


(Can be made efficient with some tricks [MSZ99])

# Range Queries: also uses the triangulation



(a)



(b)

# One problem: how to create that DT in the first place?

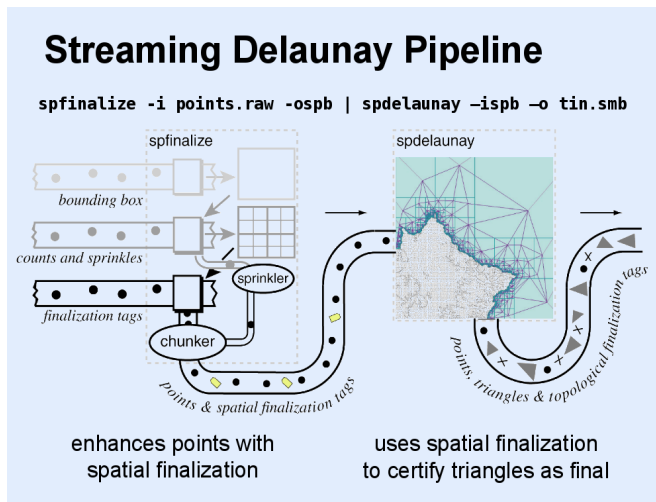
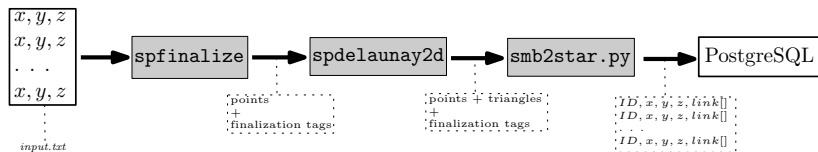


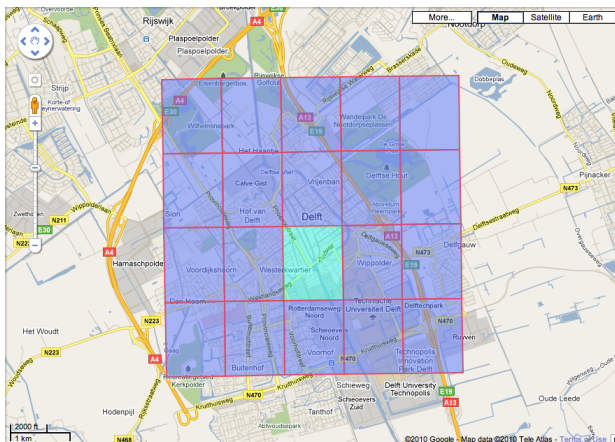
Figure from Martin Isenburg's presentation at GIScience 2006 [ILSS06]



# Streaming of geometries to construct massive TINs

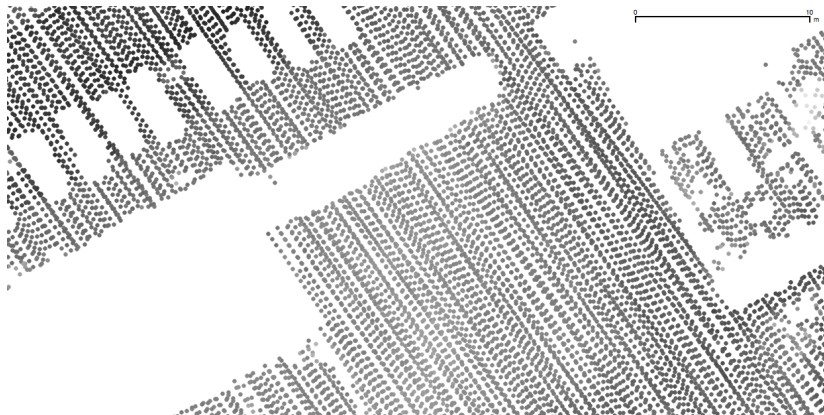


# Experiments with AHN2 datasets



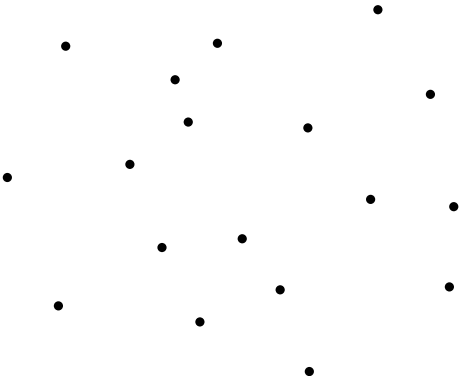
	# pts	# triangle	$degree_{avg}$	$degree_{max}$
20tiles	281 884 687	563 768 199	6.00	63
g37en1_15	8 605 090	17 201 289	6.00	39

# Experiments with AHN2 datasets



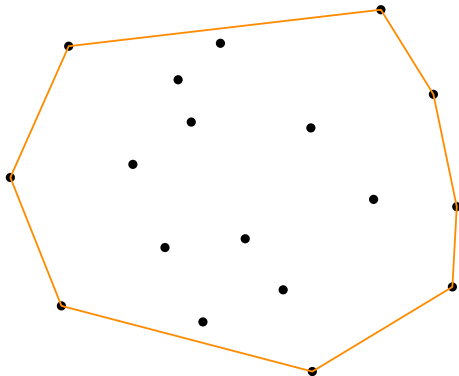
# Examples of queries: statistics about convex hull

```
20tiles=# select count(id) from points where is_convexhull(star) is true
count
-----
1173
(1 row)
Time: 333050.861 ms
```



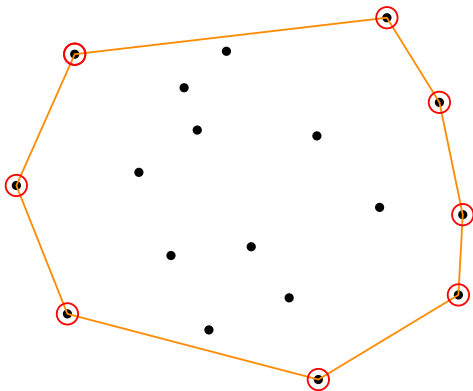
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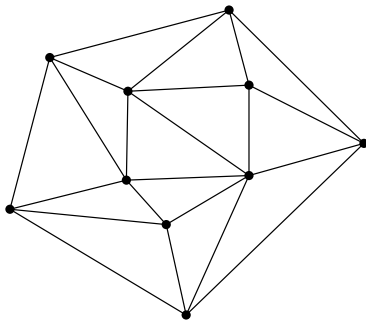
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# Examples of queries: statistics about degree of vertices

```
20tiles=# select avg(degree(star)) from points;  
      avg
```

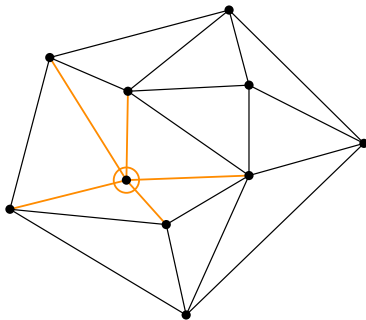
```
-----  
5.9999958142601850  
(1 row)  
Time: 332265.041 ms
```



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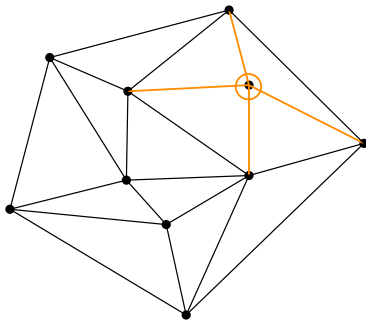




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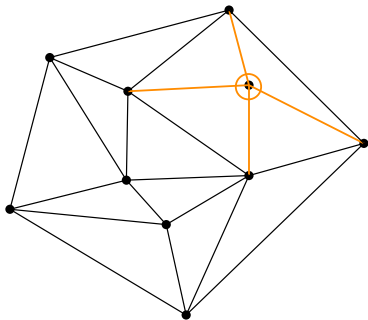
# Examples of queries: statistics about degree of vertices

```
g37en1_15=# select degree(star) as degree, count(id) from points group
by degree order by degree;
```

degree	count
3	65620
4	844625
5	2277911
6	2484212
7	2005407
8	698540
9	170214
10	37534
11	9587
12	3395
13	1552
14	772
15	456
...	(truncated) ...
37	3
39	1

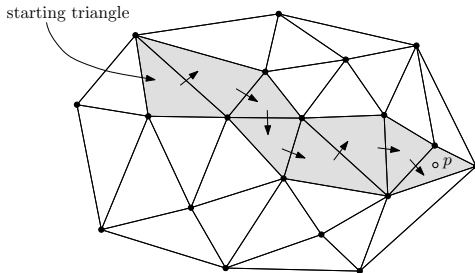
(35 rows)

Time: 39722.017 ms

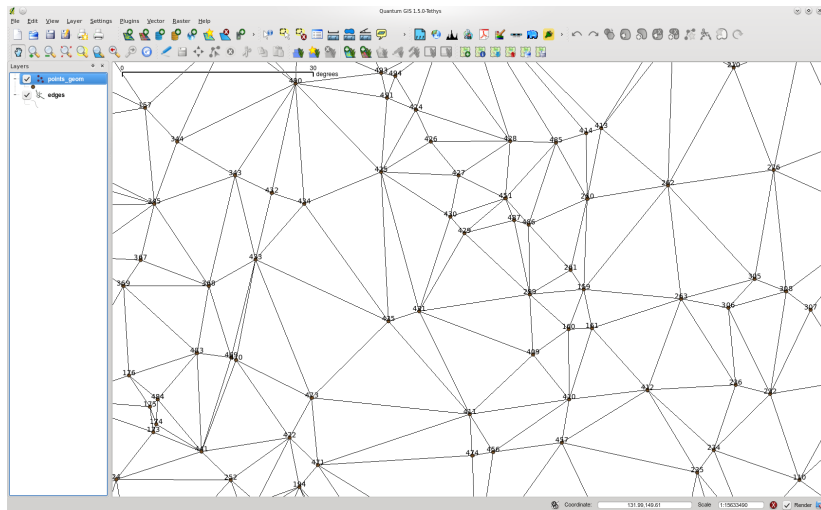


# Examples of queries: point location

```
g37en1_15=# select point_location(84111, 446666, 0, 0.2);  
WARNING: #of samples checked: 24  
WARNING: start distance is 49.843357  
WARNING: # of triangles visited is 222  
      point_location  
-----  
      (3672278,3695197,3695256)  
      (1 row)  
Time: 191.903 ms
```



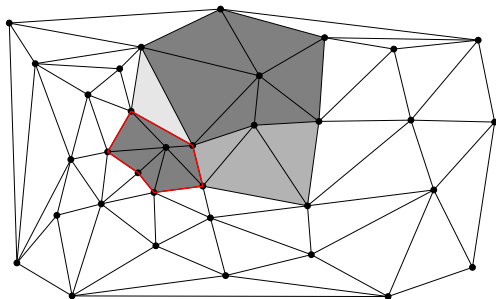
# Visualisation with a GIS



Thanks for your attention

**Hugo Ledoux**

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-  P. K. Agarwal, L. Arge, and A. Danner.  
From point cloud to grid DEM: A scalable approach.  
In A. Reidl, W. Kainz, and G. Elmes, editors, *Progress in Spatial Data Handling—12th International Symposium on Spatial Data Handling*. Springer, 2006.
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Generating raster DEM from mass points via TIN streaming.  
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Fast randomized point location without preprocessing in two- and three-dimensional Delaunay triangulations.  
*Computational Geometry—Theory and Applications*, 12:63–83, 1999.

# Populating the database

	time pipeline	time B-tree	time tr	time lasblock	width <sub>max</sub>
20tiles	178.3	24.65	36.8	<i>crashed</i>	53 003
g37en1_15	4.7	0.3	1.1	4.3	7 601